
Eddy Currents and Magnetic Calibrations in LDX using a “Copper Plasma”

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“Copper Plasma” Overview

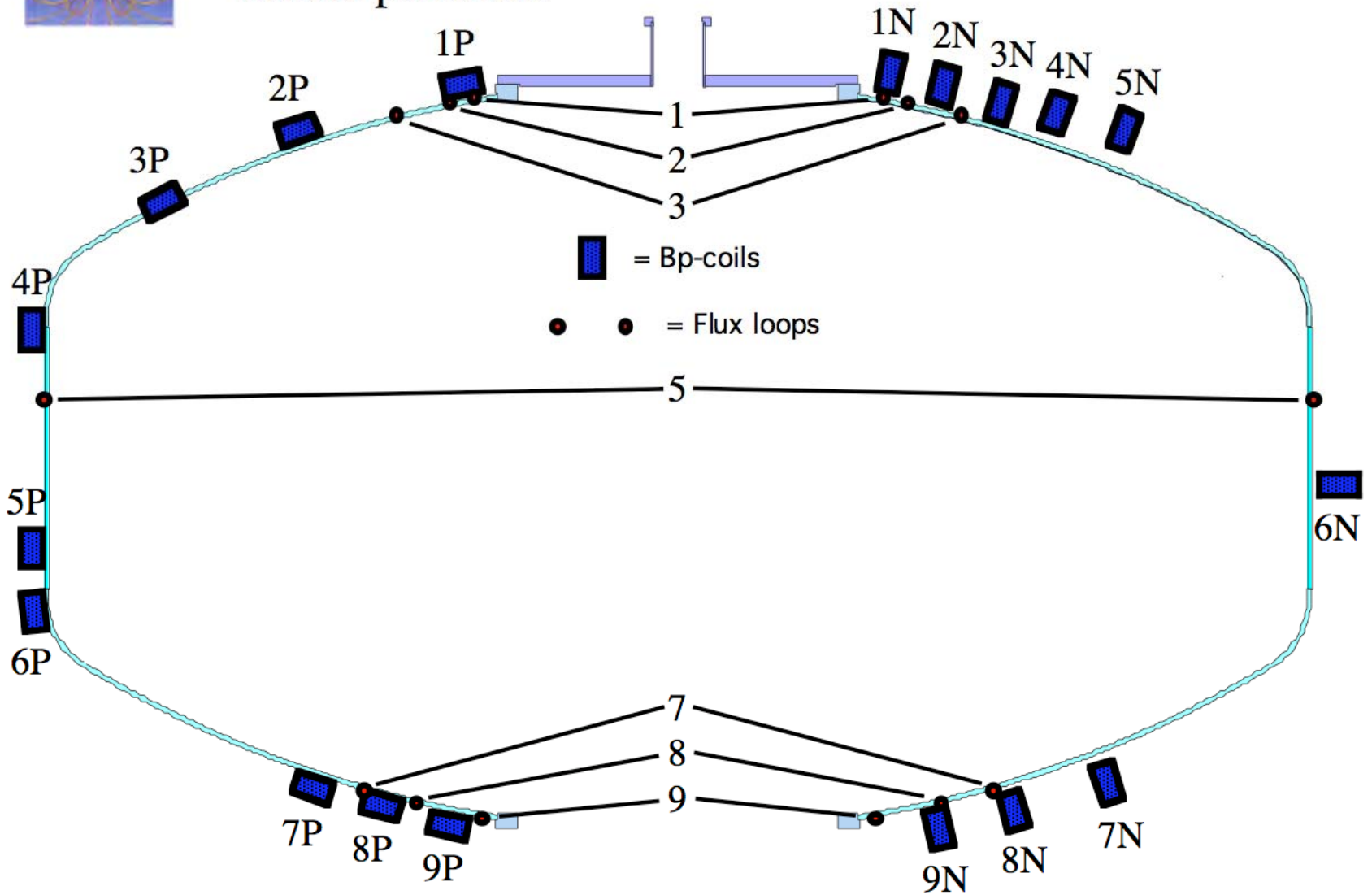
- LDX Magnetics
 - Goals
 - Calibrate magnetic diagnostics positions and gains
 - Find eddy current decay times
 - Copper Plasma Operation
 - Theory
 - Analysis
 - Results
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LDX Magnetics

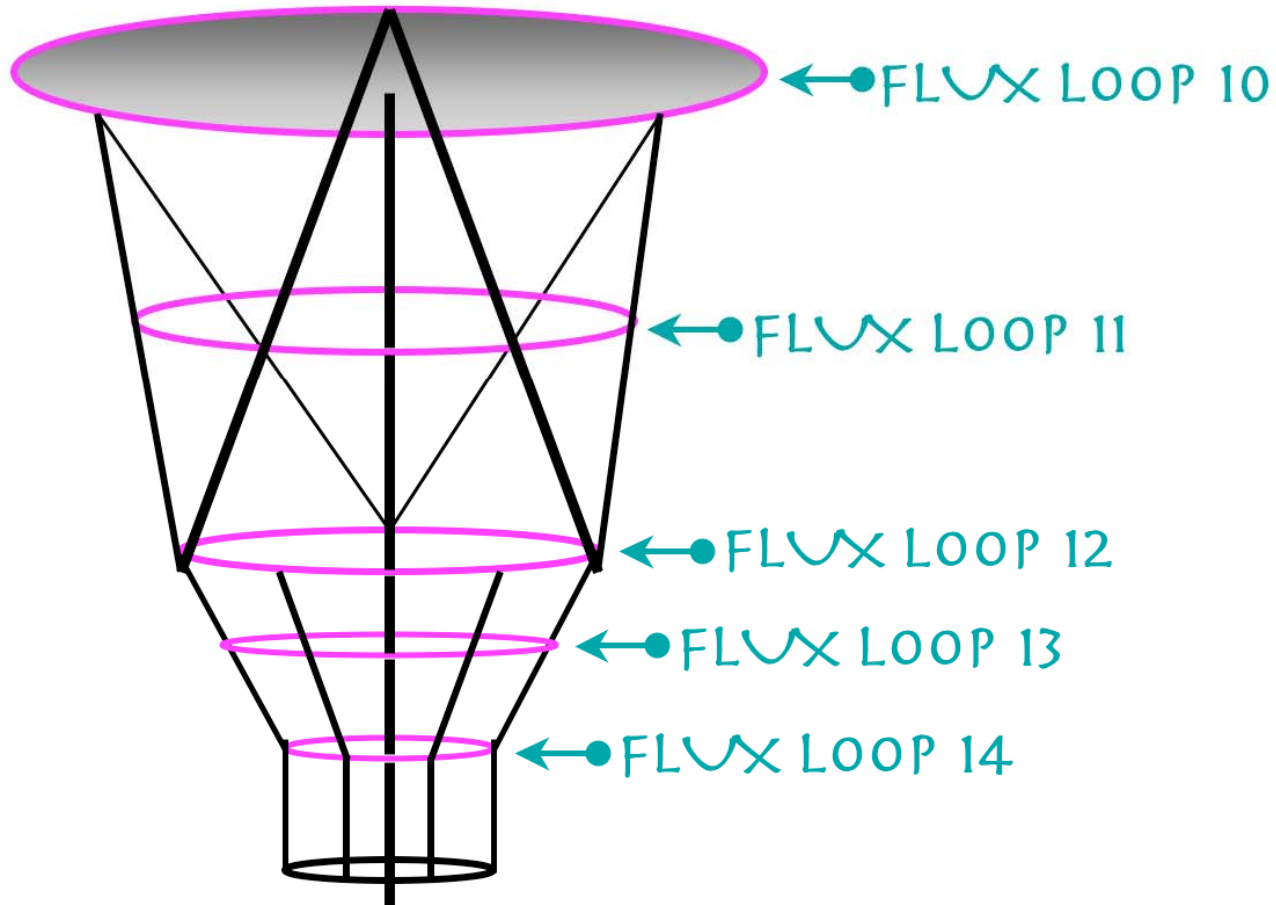
- 18 external magnetic field sensors
 - 9 parallel
 - 9 normal
 - $n \approx 1000$ turns, $a \approx 50$ cm², 15 cm length
 - 9 external flux loops
 - 5 internal flux loops
 - Sensors are time integrated using RC circuits
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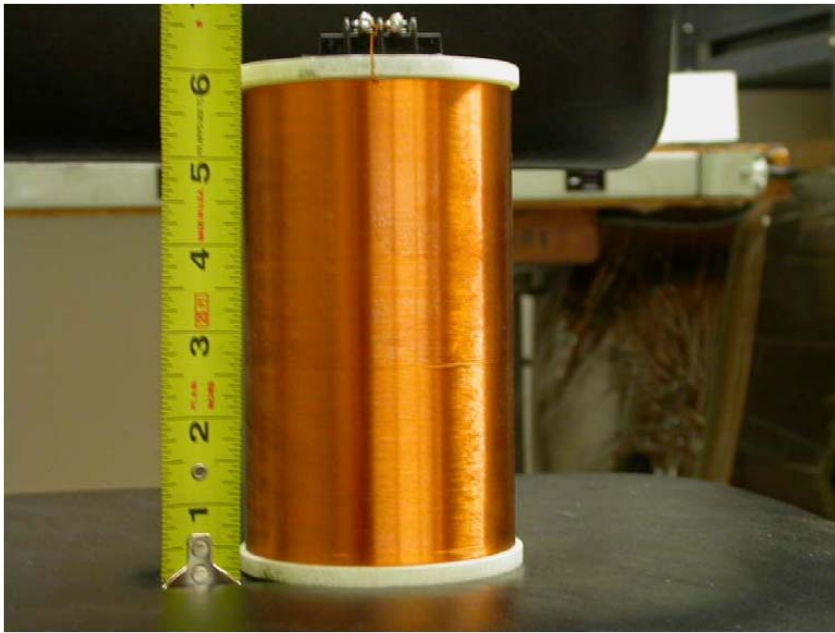


Sensor positions:



UPPER CATCHER WITH INTERNAL FLUX LOOPS





$$\vec{A}(r, z, R, Z, I) = \mu_0 I R \frac{(2 - k^2) K(k^2) - 2E(k^2)}{\pi k^2 \sqrt{(r + R)^2 + (z - Z)^2}} \hat{\phi}$$

$$k^2 \equiv \frac{4rR}{(r + R)^2 + (z - Z)^2}$$

$$B_z = \frac{1}{r} \frac{\partial}{\partial r} r A_\phi \quad ; \quad B_r = -\frac{\partial}{\partial z} A_\phi$$

$$\Phi = \int \vec{B} \cdot d\vec{a} = \oint \vec{A} \cdot d\vec{\ell} = 2\pi r A$$

$$\Phi = \int \vec{B} \cdot d\vec{a} \approx \vec{B} \cdot n\vec{a} = na(B_z \cos \theta + B_r \sin \theta)$$

$$V = \frac{1}{RC} \int -\frac{d\Phi}{dt} dt = -\frac{\Phi}{RC}$$

Goal: Calibrate Magnetics

- Positions of sensors \mathbf{r} , \mathbf{z} , $\boldsymbol{\theta}$ have been measured with rulers and laser level
 - Accuracy $\sim 3\text{mm} / 1^\circ$
 - Gains \mathbf{g} of integrator boards have been measured electronically
 - Would be better to measure positions and total gains **magnetically**
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Goal: Eddy Currents

- Magnetic levitation vertically unstable
 - Requires active feedback control
 - Fluctuations in L-coil, F-coil and plasma current magnitude
 - Fluctuations in F-coil and plasma position
 - Changing currents induce eddy currents in vessel
 - Eddy currents are picked up by magnetic diagnostics
 - Must be measured so they can be properly included in magnetic reconstruction
 - L- and F-coil eddy currents measured in vacuum shots
 - L-coil only shots – know position, know current
 - Use L-coil to induce vertical jog in F-coil, measure position with lasers and calculate current from force balance
 - **How to estimate eddy currents due to fluctuating plasma currents?**
 - Changes in plasma current magnitude and position **NOT** known
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Solution: Build “Copper Plasmas”

- 2 coils of 12 AWG copper wire
 - Approximately same radius as plasma
 - **R** = 76 cm coil - 28 turns, 91 cm coil - 25 turns
 - Built on plywood forms, forms disassembled and reassembled in vessel, coils squeezed through port
- Operated in 3 vertical positions
 - From midplane, **Z** = 0, ± 5 cm
- L-coil control system used to impose trapezoidal current pulses
 - 4s flattop @ 60A
 - Rise and fall times: 0.5s, 1s, 2s
- Operated with + and - polarity by switching coil leads
- 2 **R** x 3 **Z** x 3 times x 2 polarities x 31 sensors

Photo of copper plasma

All copper plasma parameters for 2 coils in 3 vertical positions given by :

$$\vec{X}_c \equiv \{R_1, R_2, Z_1, Z_2, Z_3, \delta Z, \Theta_1, \Theta_2, \Theta_3, \delta \Theta, \rho_1, \rho_2, \rho_3, \delta \rho, I\}$$

For copper plasma shot i , sensor j :

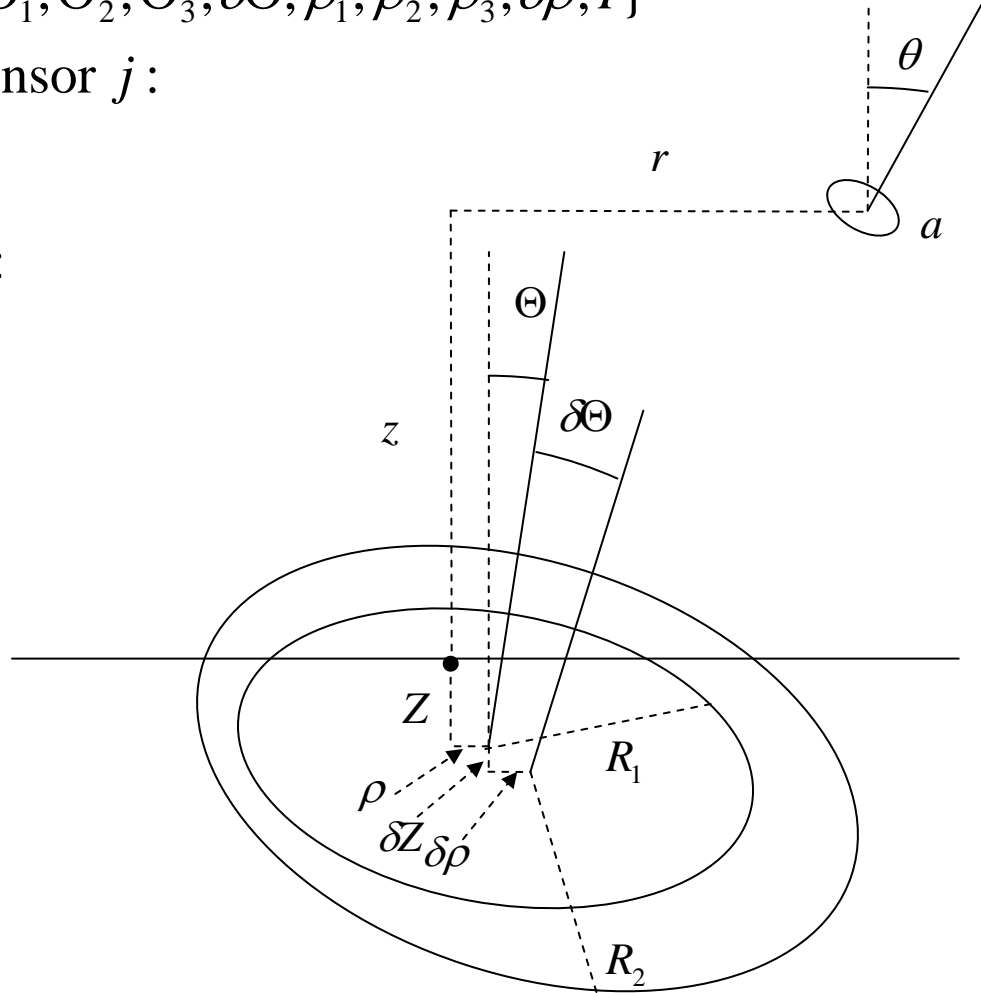
$$V_{ij} = V_{ij}(\vec{x}_{ci}, \vec{x}_{sj})$$

Copper Plasma parameters :

$$\vec{x}_{ci} \equiv \{R_i, Z_i, \Theta_i, \rho_i, I_i\}$$

Sensor parameters :

$$\vec{x}_{sj} \equiv \{r_j, z_j, \theta_j, g_j\}$$

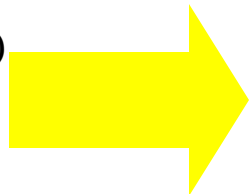


Theory: Calibrate Magnetics

- By using copper plasma with 2 different radii \mathbf{R} at 3 different heights \mathbf{Z} , can use least squares fit to find sensor calibration
 - 6 equations to find 3 or 4 unknowns
- Copper plasma parameters also not known exactly, can use least squares to find them
 - 2 \mathbf{R} x 3 \mathbf{Z} x 31 sensors = 186 equations to find 15 unknowns
- $\mathbf{V}(\mathbf{x}_c, \mathbf{x}_s)$ is non-linear
 - Linearize using measured parameters
 - Solve linear least squares
 - Adjust parameters and repeat
 - Switch between solving for \mathbf{x}_c and \mathbf{x}_s

$$\vec{x}_{ci} = f_i(\vec{X}_{c0})$$

$$\vec{x}_{sj} = \vec{x}_{sj0}$$

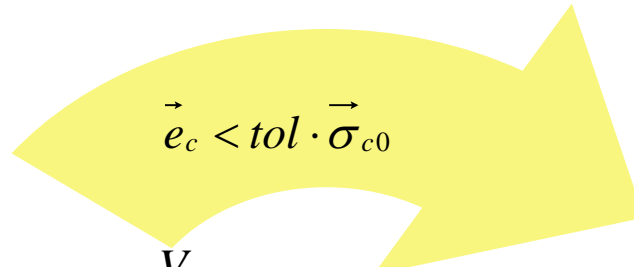


$$\frac{1}{\sigma_{V_{ij}}} \frac{\partial V_0}{\partial \vec{X}_c}(\vec{x}_{ci}, \vec{x}_{sj}) \cdot \vec{e}_c = \frac{V_{ij}}{\sigma_{V_{ij}}}$$

$$\vec{X}_c = \vec{X}_c + \vec{e}_c$$

$$\vec{x}_{ci} = f_i(\vec{X}_c)$$

$$\vec{e}_c < tol \cdot \vec{\sigma}_{c0}$$

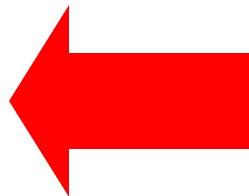


$$\frac{1}{\sigma_{V_{ij}}} V_0(\vec{x}_{ci}, \vec{x}_{sj}) \cdot e_{gj} = \frac{V_{ij}}{\sigma_{V_{ij}}}$$

$$g_j = g_j e_{gj}$$



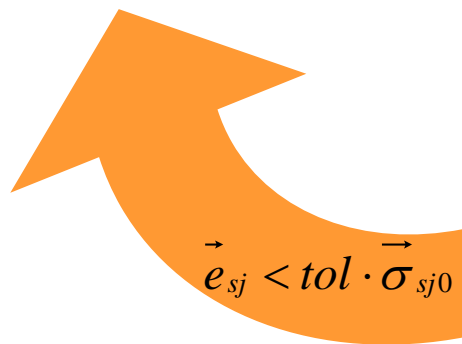
$$\vec{X}_c, \vec{x}_{sj}$$



$$\frac{1}{\sigma_{V_{ij}}} \frac{\partial V_0}{\partial \vec{x}_{sj}}(\vec{x}_{ci}, \vec{x}_{sj}) \cdot \vec{e}_{sj} = \frac{V_{ij}}{\sigma_{V_{ij}}}$$

$$\vec{x}_{sj} = \vec{x}_{sj} + \vec{e}_{sj}$$

$$\vec{e}_{sj} < tol \cdot \vec{\sigma}_{sj0}$$



Results: Calibrate Magnetics

- Flux loops give reasonable results
 - Calculated locations mostly within ~2 cm of measured
 - Gains mostly within ~10% of measured
 - χ^2 goodness of fit $\sim 10^{-3}$
 - Copper plasma location also found within 1 cm of measured
 - Magnetic sensors have very large errors
 - χ^2 goodness of fit too small for floating point
 - Because of poor results, not used in solving for copper plasma location
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Theory: Eddy Currents

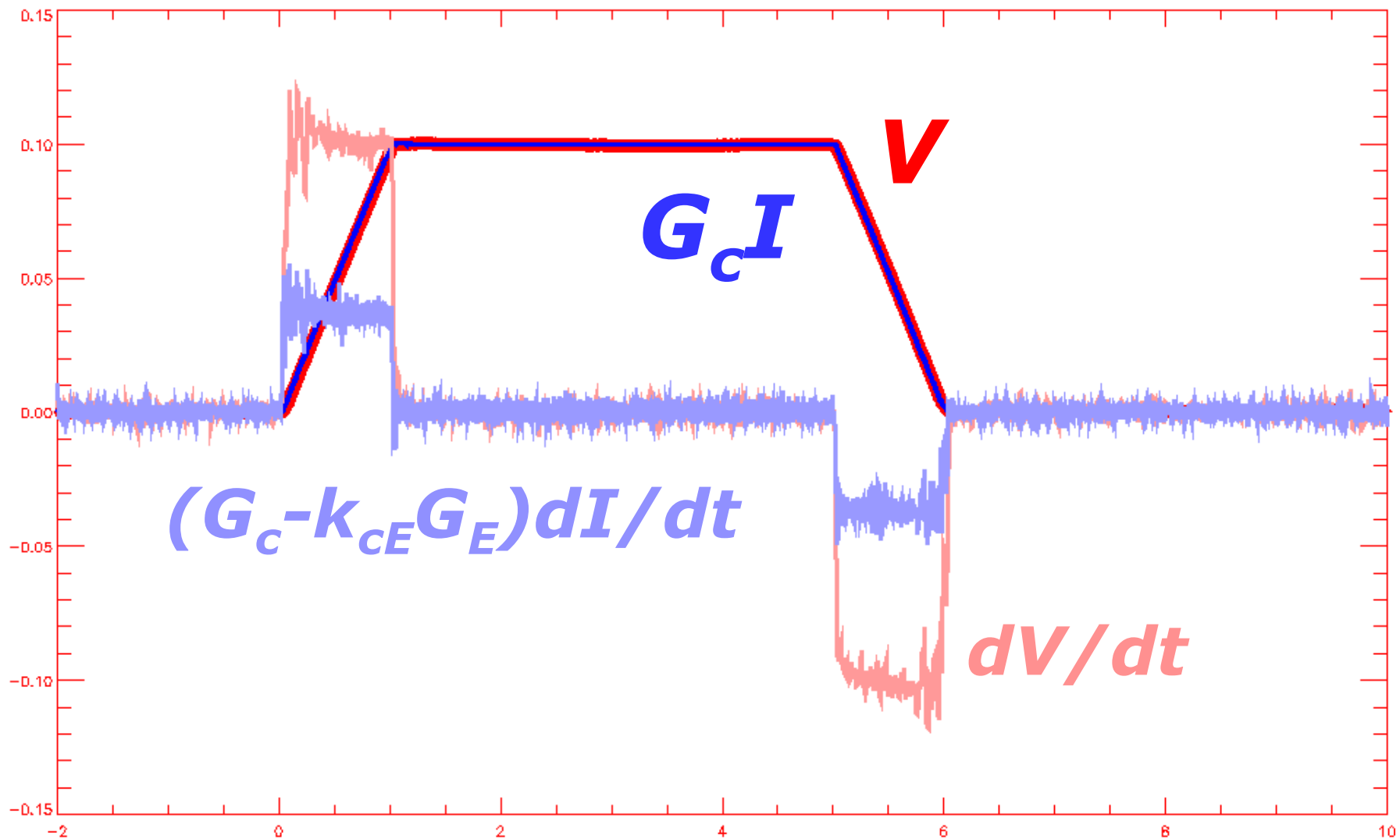
- Measured voltage \mathbf{V} given by sum of all coil and eddy currents \mathbf{I} times their respective Green's functions \mathbf{G}
- In reality, many eddy current modes occur
- To simplify, assume one dominant mode per sensor
- Final equation requires no knowledge of eddy currents to calculate decay time, τ_E

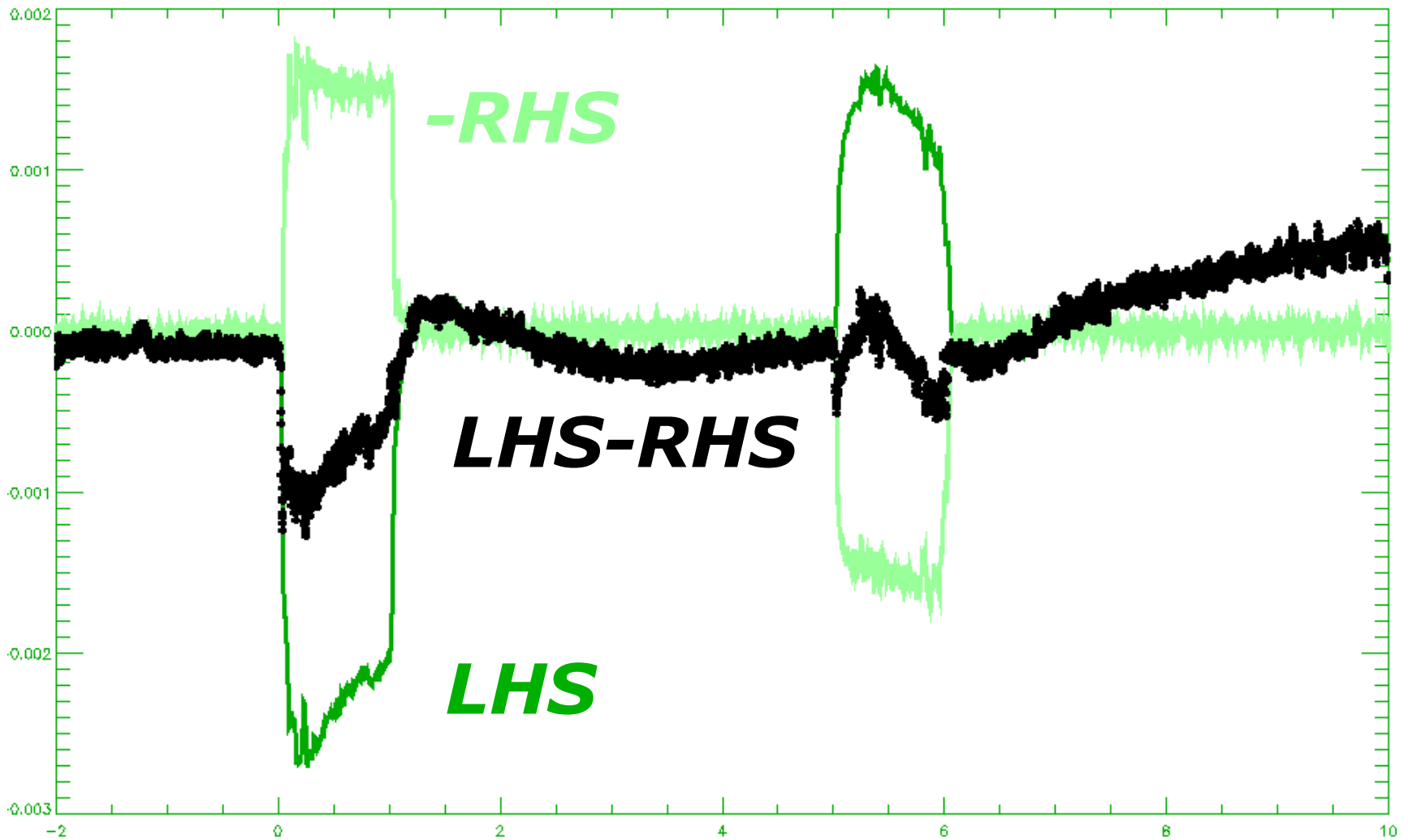
$$(1) \quad V_j = G_{c,j} I_c + \sum_E G_{E,j} I_E \quad (2) \quad \tau_E \frac{dI_E}{dt} + I_E = k_{cE} \tau_E \frac{dI_c}{dt}$$

$$(3) \quad V_j - G_{c,j} I_c = -\tau_{E,j} \left(\frac{dV_j}{dt} - (G_{c,j} - G_{E,j} k_{cE,j}) \frac{dI_c}{dt} \right)$$

Analysis: Eddy Currents

- Using the \mathbf{I} and \mathbf{V} waveforms from each of the 31 sensors and 36 experiments :
 - Steady state Green's function $\mathbf{G}_{c,j}$ is ratio of flattops $\mathbf{V0} / \mathbf{I0}$
 - This is the quantity used in sensor calibration
 - d/dt dominated Green's function $\mathbf{G}_{c,j} - k_{cE,j}\mathbf{G}_{E,j}$ is ratio of slopes $d\mathbf{V}/dt / d\mathbf{I}/dt$ at some initial time
 - τ_E found by least squares fit to Eq. 3

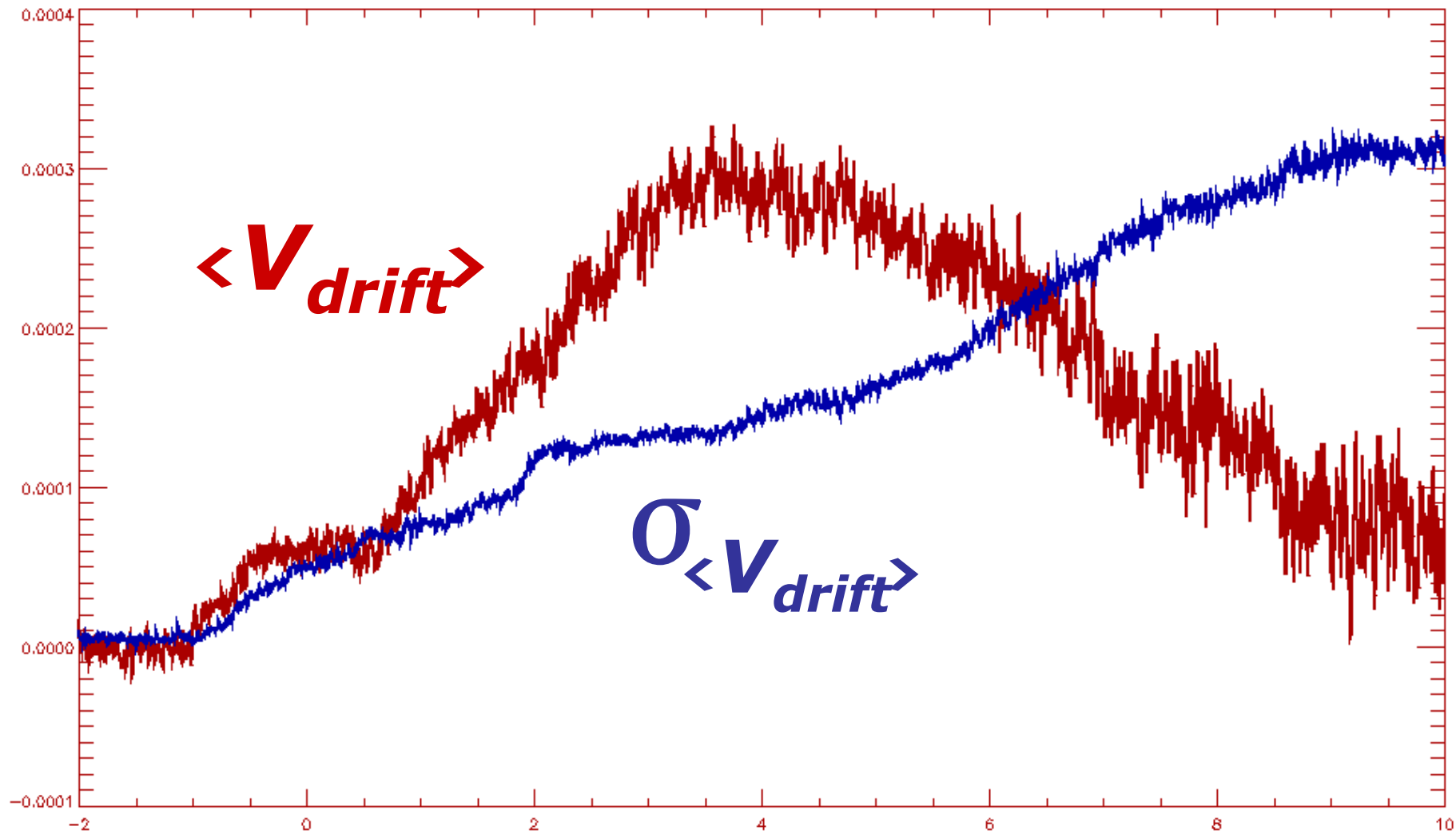




$$V_j - G_{c,j} I_c = -\tau_{E,j} \left(\frac{dV_j}{dt} - (G_{c,j} - G_{E,j} k_{cE,j}) \frac{dI_c}{dt} \right)$$

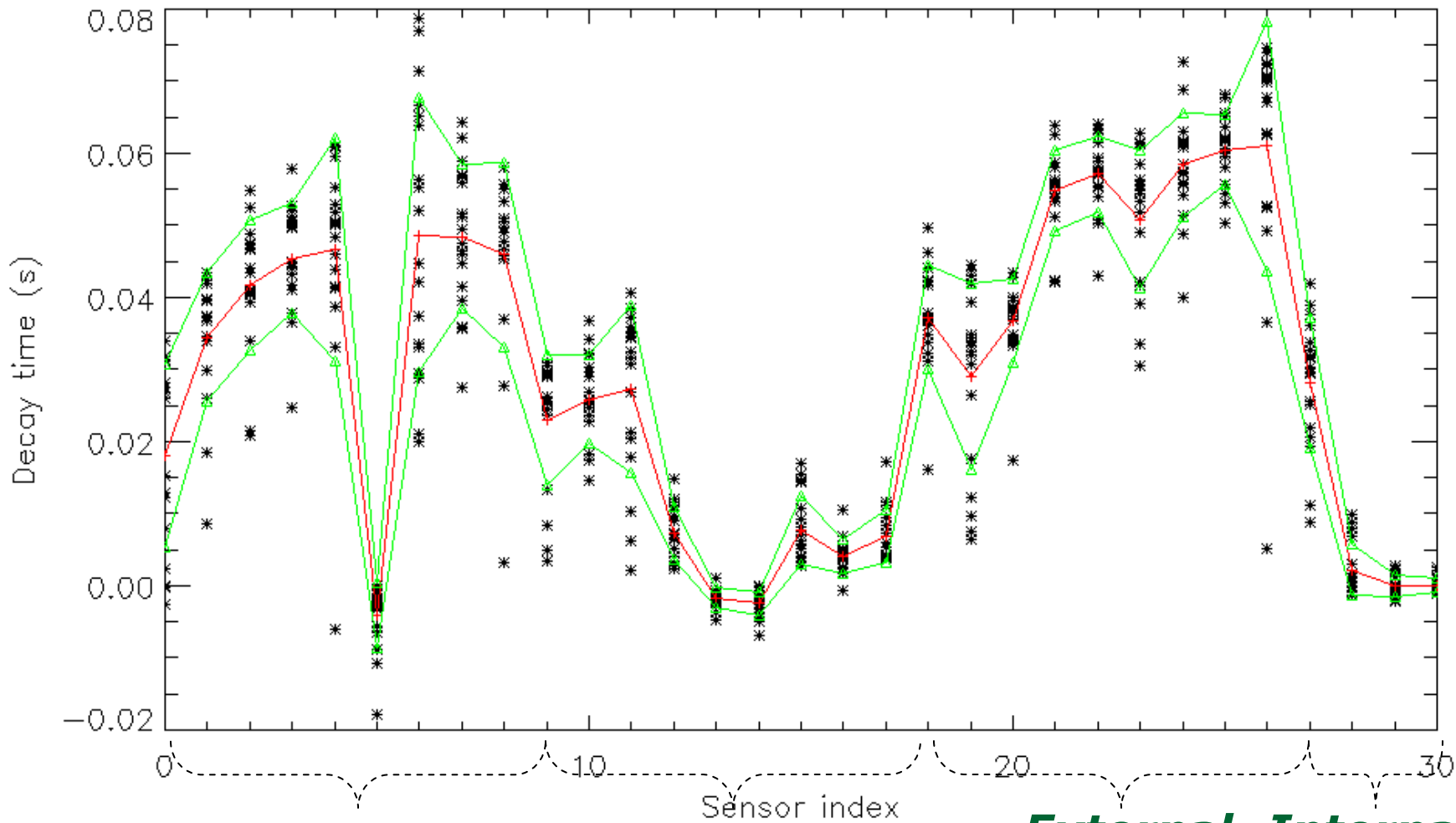
Uncertainty Analysis

- Most uncertainty due to integrator drift
 - Circuits have some drift compensation
 - In analysis, subtract initial drift before pulse
 - Optionally subtract drift during flattop and after pulse
 - Find average drift and uncertainty as a function of time from shots with no current
 - Sum shots with opposite polarity to cancel out stray fields and any reproducible drifts
 - Also some uncertainty due to power supply
 - Current is somewhat noisy
 - Difficult to fit initial **d/dt** on small, noisy signal
 - Feedback system designed for L-coil, not copper plasma
 - Leads to ringing at corners of trapezoid
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Results: Eddy Currents

- Most sensors in range 30 - 70 ms
 - Standard deviations over all shots 3 - 5 ms
 - Consistent with predictions from theory
 - Some < 10 ms or negative, standard deviations as big as τ_E
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B_{\perp}

B_{\parallel}

**External
Flux
Loops**

**Internal
Flux
Loops**

Summary

- Sensor calibration and eddy current decay time results generally consistent with previous measurements
 - Copper plasma experiment did not yield an improvement in accuracy or precision over previous measurements
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Suggestions for Future Work

- Work to reduce integrator drift
- Optimizing power supply for copper plasma could reduce noise and ringing
- Use less simplified model for copper plasma and sensors
 - Multiple windings in copper plasma
 - Possible errors in construction
 - Area and length in magnetic sensors
- Try more robust fitting schemes for calibration
- Improve calculation of $\mathbf{k}_{cE,j} \mathbf{G}_{E,j}$
 - Use different pulse shape – faster rise time, sinusoid
 - Use non-linear method to solve for both τ_E and $\mathbf{k}_{cE,j} \mathbf{G}_{E,j}$
- Do more complete analysis with multiple eddy current modes

Acknowledgements

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